
BAYESIAN MODEL AVERAGING TO PREDICT INTEREST IN ELECTRIC VEHICLES IN GERMANY

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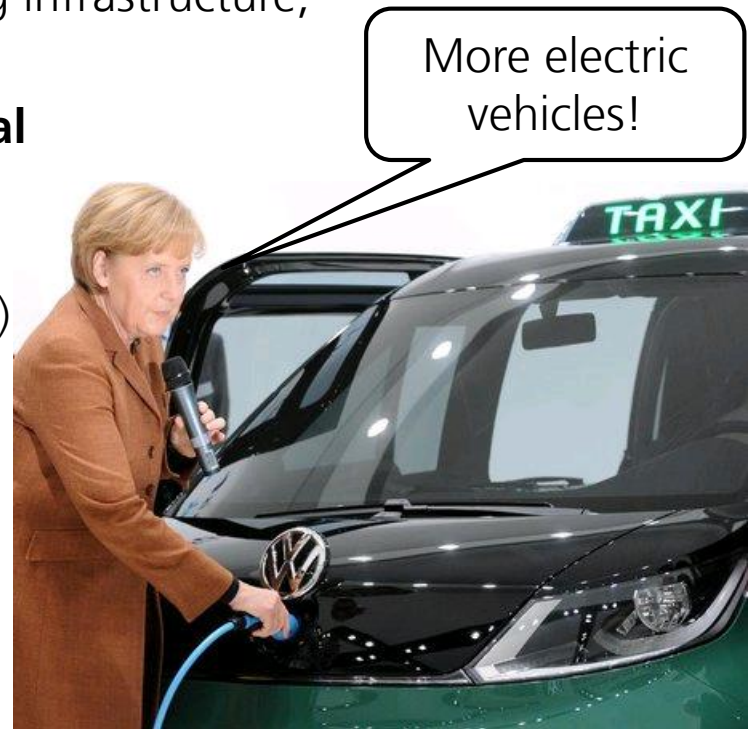
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Identification of the buyer groups is essential for policies & industry

➤ Policy makers are widely supporting electric vehicles (EVs)

- Policies that are applied differ widely, including CO₂-dependent taxes, subsidies, built-up of public charging infrastructure, pilot projects and many more
- **Identification of user groups is essential for effective policies & car makers**
- Many studies on first users (high-income, men, techies, pro-environment, high educ.)
- **but little on next groups**
- High uncertainty in influencing factors

➤ Aim: Identify the potential early Majority of electric vehicles on a sound statistical basis



Data: representative survey of 1,000 Germans on EV purchase intention

- **Representative survey of 1,017 Germans**

- Variables on

- **Interest in EV, purchase intention**

- Symbolic value of cars (on 1 – 7 likert scale):

- “Using a ICE / EV I can determine my route by myself ” (*Autonomy*)
 - “An ICE / EV takes me everywhere” (*Freedom*)
 - Willingness to pay more (WTPM) in % for EV

Variable	mean	SD
Age	48.3	16.6
HH members	2.4	1.2
Technology affinity	4.4	0.9
Availability ICE	5.2	1.3
Availability EV	3.4	1.7
Independence ICE	5.3	1.2
Independence EV	3.9	1.6
Freedom ICE	5.4	1.0
Freedom EV	3.7	1.6
Autonomy ICE	5.5	1.0
Autonomy EV	4.0	1.6
WTPM	5.3	9.9

- Classification into **adopter groups** following Peters et al. (2011)

- Participant owns an EV → *Innovator*
 - Participant wants to buy & is interested in EVs → *early adopter*
 - Participant does not want to buy but is interested in EVs → **early majority**

Results: Single logistic model

- Rogers' Adopter groups for EVs in survey:
 - 0.4% innovators own an EV; 1% with purchase intention → early adopter
 - **49% are interested → Majority group → want to understand them**
- Dependent variable: **Interest in EV?** (binary: yes/no)
- Results **of logistic regression model:**

Predictor	Estimate	Std. Error	p-value
(Intercept)	-5.16	0.63	< 2e-16 ***
Technology affinity	0.75	0.09	9.2e-16 ***
WTPM in %	0.06	0.01	2.5e-11 ***
Education	0.20	0.07	0.0020 **
Autonomy EV	0.35	0.05	1.4e-11 ***
Freedom ICE	-0.31	0.08	2.4e-4 ***
Drivers license	1.10	0.28	6.8e-5 ***

- **Problem: many other factors play role & model seems overly confident**

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Method: Bayesian model averaging compensates for over-confidence of simple regression

- BMA to account for **model uncertainty** (significance and size of effect depends on the number of variables chosen for the regression)
- BMA provides a coherent way to integrate model uncertainty (Hoeting et al. 1999)
- Result: **posterior distribution for the coefficient** given data as the average of individual models each weighted by its posterior model probability:

$$\text{pr}(\beta|D) = \sum_{k=1}^K \text{pr}(\beta|M_k, D) \text{pr}(M_k|D)$$

Probability of coeff's given data

Probability of coeff's given model+data

Probability of model given the data

- Difficult: posterior model probabilities due to integrated likelihood (high-dimensional integral), and the large number of possible models
- We use the BMA package & R statistical software with **2,000 models total**

The top ten models have different sizes and lead to different coefficients

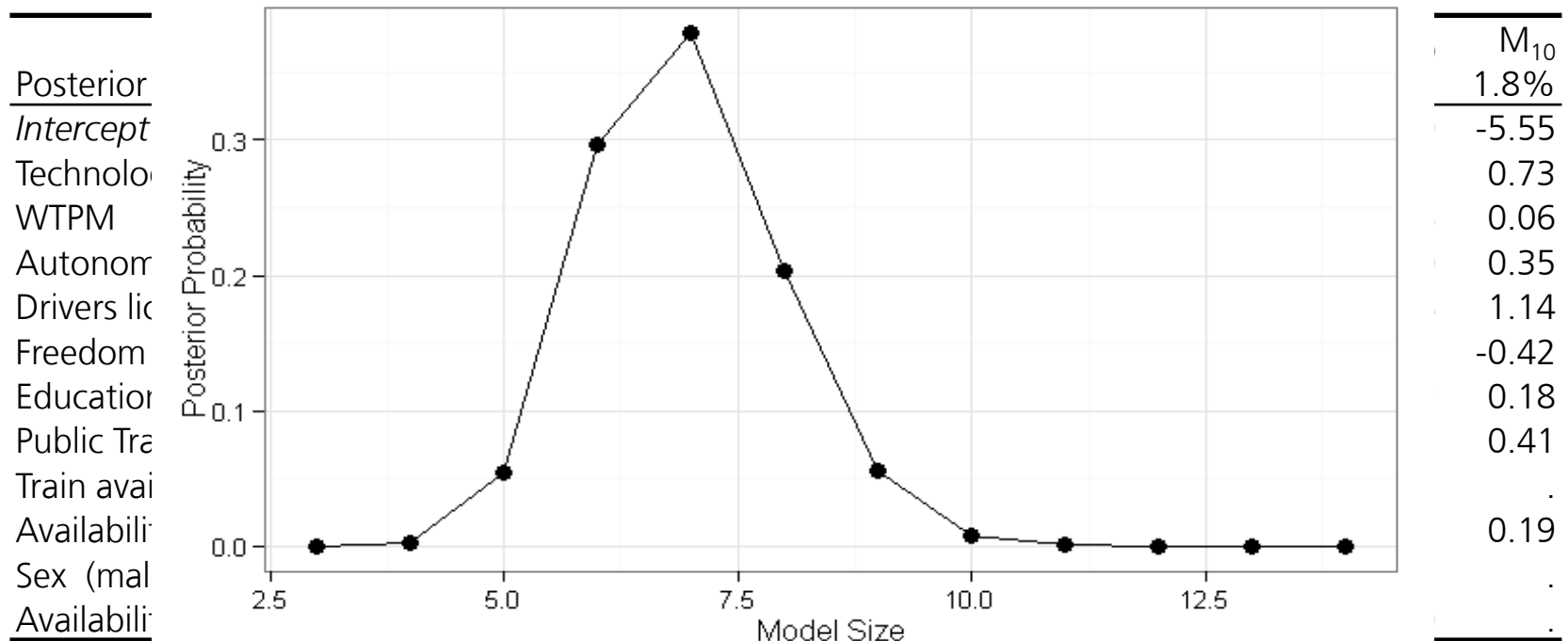
- Top ten models by posterior model probability (approx. related to BIC)
- As expected, coefficients vary and single model p-values are over-confident

	M ₁	M ₂	M ₃	M ₄	M ₅	M ₆	M ₇	M ₈	M ₉	M ₁₀
Posterior Probability	13.1%	5.0%	3.8%	3.2%	3.0%	3.0%	2.5%	2.2%	2.1%	1.8%
<i>Intercept</i>	-5.16	-5.49	-5.39	-4.52	-4.89	-4.97	-5.18	-5.19	-5.20	-5.55
Technology affinity	0.75	0.75	0.75	0.77	0.76	0.76	0.74	0.72	0.75	0.73
WTPM	0.06	0.06	0.06	0.06	0.06	0.06	0.06	0.06	0.06	0.06
Autonomy EV	0.35	0.35	0.35	0.35	0.34	0.34	0.36	0.36	0.30	0.35
Drivers license (yes)	1.10	1.26	1.19	1.23	1.32	1.39	0.99	1.08	1.08	1.14
Freedom ICE	-0.31	-0.28	-0.27	-0.31	-0.27	-0.28	-0.43	-0.30	-0.31	-0.42
Education	0.20	0.18	0.18	.	.	.	0.20	0.20	0.19	0.18
Public Transp. (yes)	.	0.36	.	.	.	0.41	.	.	.	0.41
Train available	.	.	0.40	.	0.48
Availability ICE	0.16	.	.	0.19
Sex (male)	0.28	.	.
Availability EV	0.10	.

- Bayesian model averaging: weighted average of top 2,000 models!**

The top ten models have different sizes and lead to different coefficients

- Top ten models by posterior model probability (approx. related to BIC)
- As expected, coefficients vary and single model p-values are over-confident



- **Bayesian model averaging: weighted average of top 2,000 models!**

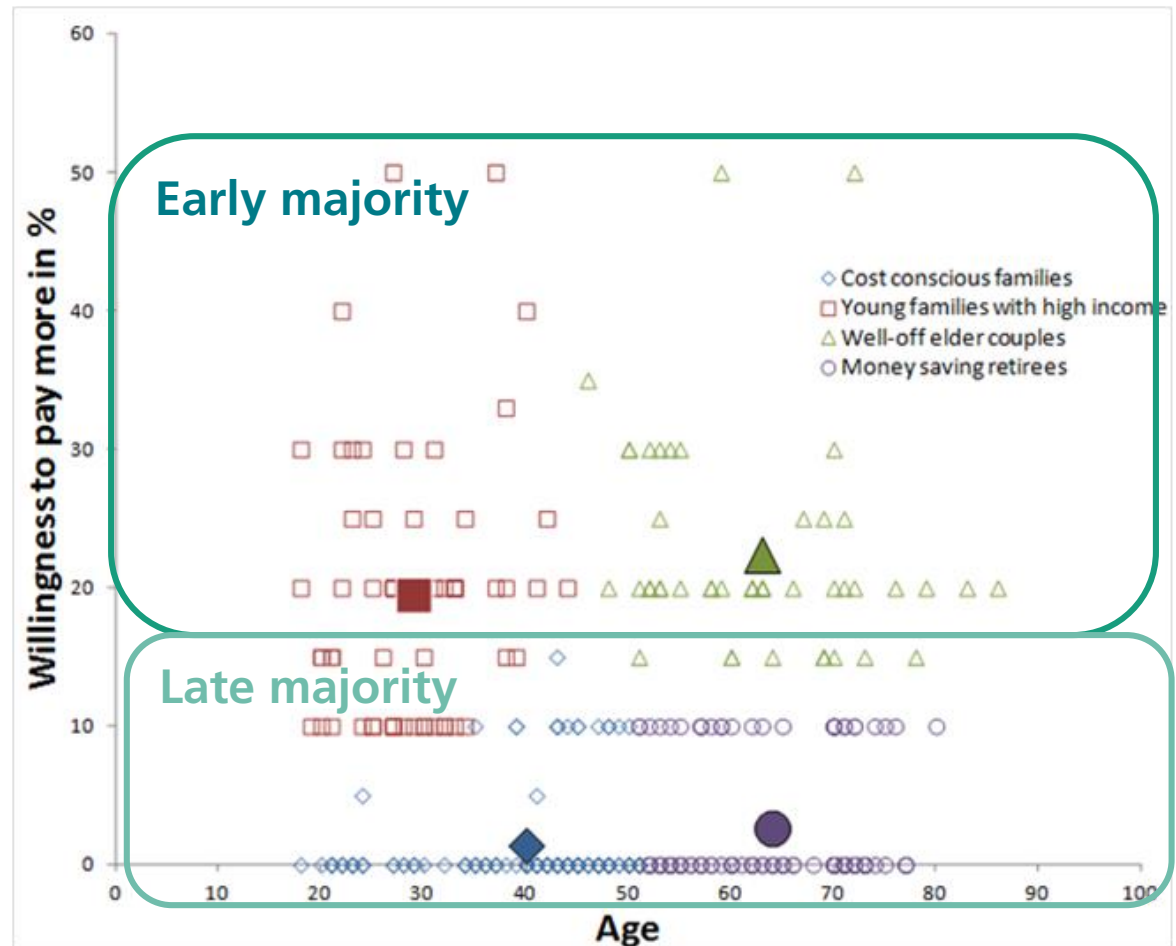
Results: Factors influencing interest in EV including model selection uncertainty

	Predictor	Posterior Effect Probab. P($\beta \neq 0$)	Posterior Mean	Posterior SD
<ul style="list-style-type: none"> Combined effect from all models weighted by model probability Uncertainty much more transparent 	Technology affinity	100.0	0.742	0.096
	Willingness to pay more	100.0	0.063	0.010
	Autonomy EV	100.0	0.337	0.059
	Drivers license	99.3	1.161	0.317
<ul style="list-style-type: none"> Probability that $\beta \neq 0$ 	Freedom ICE	85.2	-0.270	0.149
	Education	64.7	0.123	0.106
<ul style="list-style-type: none"> Mean and SD of coeff after all model runs 	Public Transport Avail.	30.1	0.118	0.203
	Train Available	27.7	0.127	0.232
	Availability ICE	18.3	0.033	0.079
	sex	16.7	0.052	0.132
	Availability EV	14.9	0.016	0.044
	Autonomy ICE	7.9	-0.016	0.070
	Working	6.4	0.015	0.069
	Children	5.1	-0.012	0.066
	Independence ICE	4.7	-0.006	0.038
	Independence EV	3.4	0.002	0.018
	HH members	3.0	0.002	0.016
	Climate	2.2	0.003	0.034
Age	1.7	0.000	0.001	
Freedom EV	1.7	0.000	0.011	

compare these to p-values!

The next big group of adopters can be divided into subgroups

- Use k-means clustering to find subgroups
- Early and late majority can be divided by willingness to pay more
- Both have younger and older group
- Socio-demographics differ too



Discussion and conclusions

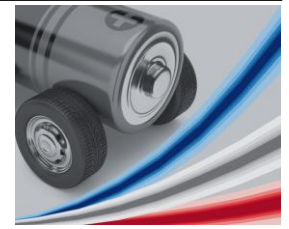
Discussion and further research

- Some factors are rather pre-conditions and discriminative
- Interest, purchase intention and willingness to pay more currently directly related

Conclusions

- **Interest in new technology** and **symbolic value of car** (no or low association of freedom with conventional vehicles) are **most important distinguishing factors** for next big group of EV users
- **Bayesian model averaging** is coherent method against model uncertainty

Thank you for your attention



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Sources:

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Peters, A., Agosti, R., Popp, M., Ryf, B. (2011): Electric mobility – a survey of different consumer groups in Germany with regard to adoption. Proceedings to ECEEE Summer Study, June 2011, Belambra Presqu'île de Giens, France.

Hoeting, J. A., Madigan, D., Raftery, A. E., & Volinsky, C. T. (1999). Bayesian model averaging: a tutorial. *Statistical science*, 382-401.

Adrian Raftery, Jennifer Hoeting, Chris Volinsky, Ian Painter and Ka Yee Yeung (2017). BMA: Bayesian Model Averaging. R package version 3.18.7. <https://CRAN.R-project.org/package=BMA>

Bayes' Theorem

- Definition of conditional probability:

$$P(A | B) P(B) = P(A \cap B)$$

- This implies:

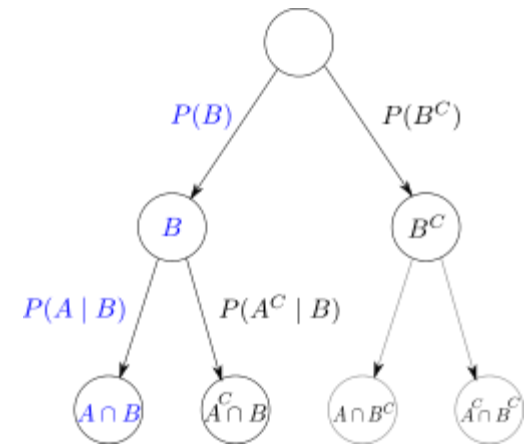
$$P(A | B) = \frac{P(A \cap B)}{P(B)} = \frac{\frac{P(A \cap B)}{P(A)} \cdot P(A)}{P(B)} = \frac{P(B | A) \cdot P(A)}{P(B)}$$

- Bayes' Theorem results:

$$P(A | B) = \frac{P(B | A) \cdot P(A)}{P(B)}$$

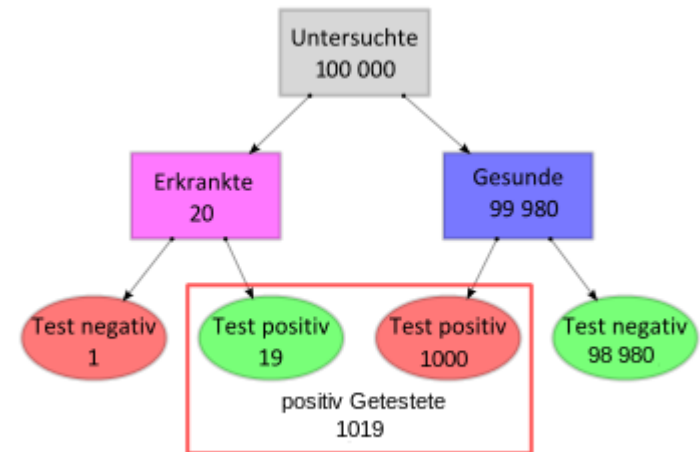
- Different generalisations exist:

$$P(A_i | B) = \frac{P(B | A_i) \cdot P(A_i)}{P(B)} = \frac{P(B | A_i) \cdot P(A_i)}{\sum_{j=1}^N P(B | A_j) \cdot P(A_j)}$$



Example

- Medical (and statistical) tests can be wrong
- Let K denote the state Sickness and T the test result
- For sick people, the test is correct in 95 % of the cases, i.e. $P(T|K) = 0.95$
- The test yields "sick" also for 1% of the healthy people, i.e. $P(T|\sim K) = 0.01$.
- What is the probability that a tested person is actually sick?



$$P(K | T) = \frac{P(T | K)P(K)}{P(T | K)P(K) + P(T | K^c)P(K^c)} = \frac{0,95 \cdot 0,0002}{0,95 \cdot 0,0002 + 0,01 \cdot 0,9998} \approx 0,0186$$

- Despite the positive test result only about 2% are actually sick with this rare disease!
- Accuracy of tests is important for very rare diseases (e.g. HIV – a second test is obligatory in Germany)

Bayesian inference

- Let x denote a random variable from distribution $p(x|\theta)$ with unknown parameter θ
- Data points $\mathbf{x} = x_1, \dots, x_n$ have been observed
- The prior distribution of the parameter is assumed to be $p(\theta|\alpha)$
- The probability to observe exactly the data \mathbf{x} if θ had exactly the value θ is given by the likelihood function: $L(\theta|\mathbf{x}) = p(\mathbf{x}|\theta)$
- **Result:** The Posterior distribution for the Parameter θ under the data is

$$p(\theta | \mathbf{X}, \alpha) = \frac{p(\mathbf{X} | \theta)p(\theta | \alpha)}{p(\mathbf{X} | \alpha)} \propto p(\mathbf{X} | \theta)p(\theta | \alpha)$$

where

$$p(\mathbf{X} | \alpha) = \int_{\theta} p(\mathbf{X} | \theta)p(\theta | \alpha) d\theta$$

- Summary:

$$\text{posterior} = \frac{\text{prior} \times \text{likelihood}}{\text{evidence}}.$$

Application 4: Bayesian Model Averaging

- Linear models with several variables are very common:

$$y = \alpha_\gamma + X_\gamma \beta_\gamma + \varepsilon \quad \varepsilon \sim N(0, \sigma^2 I)$$

- Yet, the choice of variables can heavily influence results! Which model to choose?
- With K parameters 2^K models M_γ are possible!
- In the following: dependent variable: Interest in electric vehicles (EV); independent variables: Socio-economic attributes and other items.
- A single model suggests very low uncertainty:

	Estimate	Std. Error	z value	Pr(> z)							
(Intercept)	-5.218129	0.623700	-8.366	< 2e-16	***						
Techaffin	0.770285	0.092990	8.284	< 2e-16	***						
WTPM	0.063270	0.009491	6.666	2.62e-11	***						
education	0.198189	0.064894	3.054	0.00226	**						
autonomyEV	0.362730	0.051936	6.984	2.87e-12	***						
freedomICE	-0.323808	0.081642	-3.966	7.30e-05	***						
drivers_licenseyes	1.149443	0.275245	4.176	2.97e-05	***						

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Hoeting, J. A., Madigan, D., Raftery, A. E., & Volinsky, C. T. (1999). Bayesian model averaging: a tutorial. *Statistical science*, 382-401.

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